

## **User Guide**

**I ndustri al sewing machi ne**

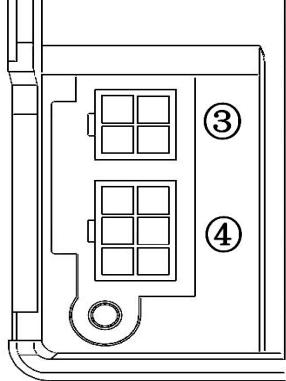
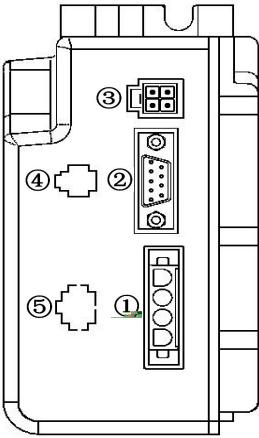
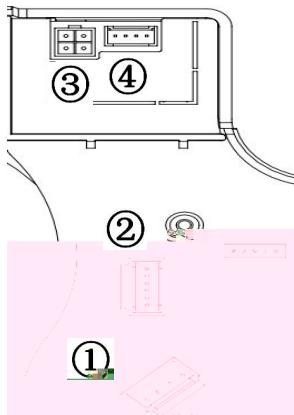
**Thank you for purchasing our products.**

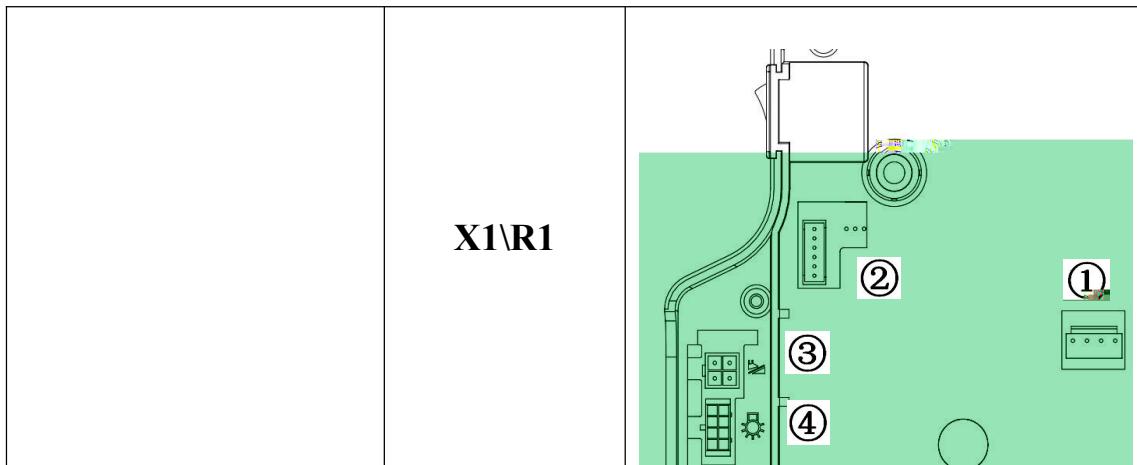
**For your use safety, please must read the instruction manual before use.**





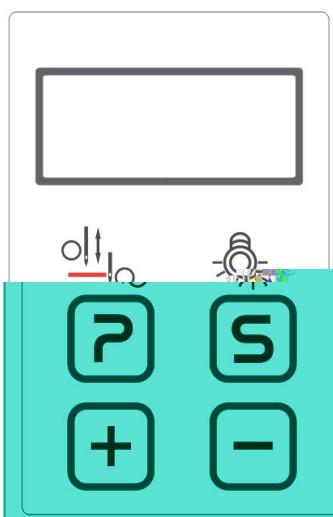
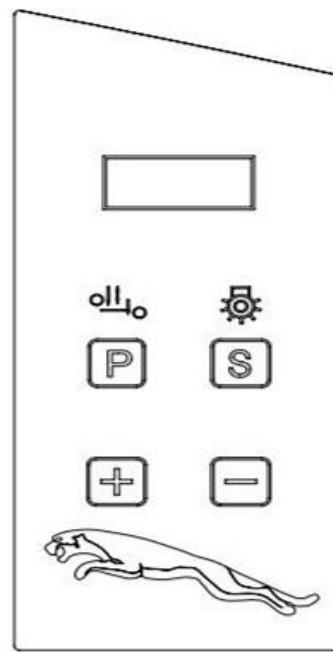
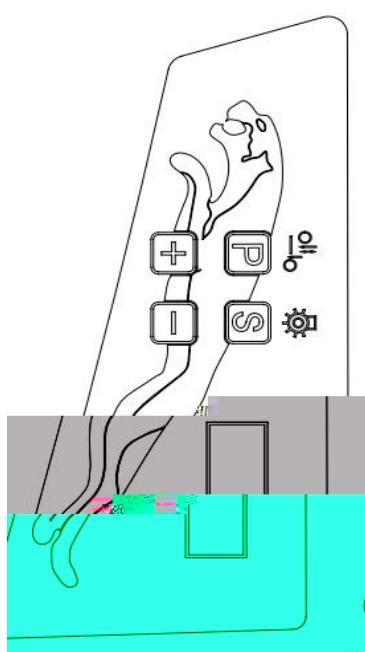
Up-down needle position	Yes( need device of needle position )	Yes	Yes	Yes
Over current, overload	Yes	Yes	Yes	Yes

<b>Port definition</b>	<b>M-7SE2\Q1\S1</b> <b>Built-in</b>	
	<b>M-6SD2</b>	
	<b>W1\V1\P1\N1</b>	



### Operation panel description

- 1)  : Working mode, switch the up-down needle position; Parameter mode, setting the parameter.
- 2)  : Working mode, switch the LED light; Parameter mode, save the parameter.
- 3) 、  : Working mode, adjust the motor speed; Parameter mode, choice and adjust for parameter.

M-6SD2\M-7SE2\Q1\S1	X1\R1	W1\V1\P1\N1
		

## Parameter adjusting and example

1. The parameter adjusting of four digital Nixie tube display.

Adjust the speed by press the “”, “

1.2 In standby interface ,press the “

1.3 In standby interface ,press the “

1.4 Enter in and change the system parameter

When the power is on ,press the“

②Press the “

③After choose the parameter , press the“

④Press the “

1.5 The setting of motor rotate way:

When the power is on ,press the“

②Press the “

③chosen parameter,press “<img alt="P icon" data-bbox="385 645 425 675}” ,using “<img alt="plus sign icon" data-bbox="495 645 535 675}”</p>

## Error code and parameter

Error code.	Meaning	Code
Er01	The error of needle position	The motor hall is broken The wheel magnet fall off The connecting of needle signal line is not good. Hanging component is connected at wrong position (NO.⑤output terminal of the needle signal connection)
Er02	Can't test the motor signal	①pedal signal line connect not good or broken.
Er03	The hall or phase of motor is wrong.	①The connecting of 9 needle signal line is not good ②The motor hall is broken.
Er04	The protection of locked-rotor	The motor is overloading.
Er05	The hardware is over-current.	The connecting of motor power line is not good. The motor is overloading.
Er07	The serial communication	The connecting of motor signal line is not good.

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<b>P-05</b>	Accelerate the speed	2000~4000	3500	3500 rpm
<b>P-06</b>	Set the needle sewing	0~999	0	
<b>P-07</b>				Retention parameter
<b>P-08</b>				Retention parameter
<b>P-09</b>				Retention parameter
<b>P-10</b>	Automatic Mode switch	0~1	0	No.1 code it's Automatic mode, the function close when turn off power
<b>P-11</b>			0	Retention parameter
<b>P-12</b>			0	Retention parameter
<b>P-13</b>	Selection of motor	0~1	0	1: Old motor 0: normal motor
<b>P-14</b>	Maximum current	50~1000	280	
<b>P-15</b>	Needle position setting	0~1	1	1:means detecting needle position, 0 :means no detect